

# Optimal Adaptive vs. Optimal Group Sequential Designs

Keaven Anderson<sup>1</sup> and Qing Liu<sup>2</sup>

<sup>1</sup>Merck Research Laboratories

<sup>2</sup>Johnson & Johnson Pharmaceutical Research and  
Development

BASS XI

November 2, 2004

# Outline

- Introductory example
- Adaptive design
  - Background
  - Conditional error functions
  - Optimization
- Optimal group sequential design
- Examples comparing optimized adaptive and optimized group sequential designs
- Summary and unresolved issues

# What is adaptive design?

- For this paper:
  - Sample size adjustment at a single interim analysis
  - This is a very narrow definition!

# Designs with Interim Analysis

Design	Analysis 1 n=	Analysis 2 n=	Analysis 3 n=
Fixed (no interim)	1051	NA	NA
2-stage group-sequential	440	1225	NA
3-stage group-sequential	306	679	1347
2-stage adaptive (LC)	430	679 to 1402	NA
2-stage adaptive (PH)	700	903 to 1866	NA

# Tradeoffs

- Time and expense for an interim analysis
- Do final analysis at the 'right sample size' versus at a predictable sample size
- Partial knowledge of results from adjusted sample size (small sample size means 'looks good!')
- Statistical efficiency?
  - PH (whatever it is) looks bad!

# Background

- Adaptive designs allow ‘redesign’ of trial based on interim data
  - have been criticized for not using sufficient statistics
- Tsiatis and Mehta, *Biometrika*, 2003 prove group-sequential can be used to improve on a given adaptive design
  - May require additional interim analyses compared to adaptive
- Jennison and Turnbull, *Statistics in Medicine*, 2003
  - Suggest that if group sequential design is planned for all contingencies, it will have better power and sample size characteristics across a broad range of treatment differences than an adaptive design
  - Use adaptive design basing adjustment on interim estimated treatment difference

# Background

- Posch, Bauer and Brannath, *Statistics in Medicine*, 2003
  - Start with a given 2-stage group sequential design
  - Find optimal adaptive design with
    - same timing of interim analysis
    - same critical value at interim analysis
    - restricts maximum sample size
    - sets second stage sample size based on conditional power for a minimum treatment effect of interest
    - minimize expected sample size averaged over a fixed set of alternatives
    - These designs can improve average sample size over given group sequential designs
- Design strategy presented here is a generalization
  - optimize over a broad class of conditional error functions
    - replaces need to set maximum sample size
  - does not restrict timing or critical value of interim analysis
  - minimize expected value of loss function over a prior distribution for treatment effect size

# Background

- Lokhnygina and Tsiatis, 2004
  - Fully optimized 2-stage adaptive designs
    - Not confined to a limited class as here
    - Otherwise, the optimization objective is the same
    - Dynamic programming algorithm for optimization



STATISTICS IN MEDICINE

*Statist. Med.* 2003; **22**:971–993 (DOI: 10.1002/sim.1457)

## Mid-course sample size modification in clinical trials based on the observed treatment effect

Christopher Jennison<sup>1,\*†</sup> and Bruce W. Turnbull<sup>2</sup>

<sup>1</sup>*Department of Mathematical Sciences, University of Bath, Bath BA2 7AY, U.K.*

<sup>2</sup>*Department of Statistical Science, 227 Rhodes Hall, Cornell University, Ithaca, New York 14853-3801, U.S.A.*

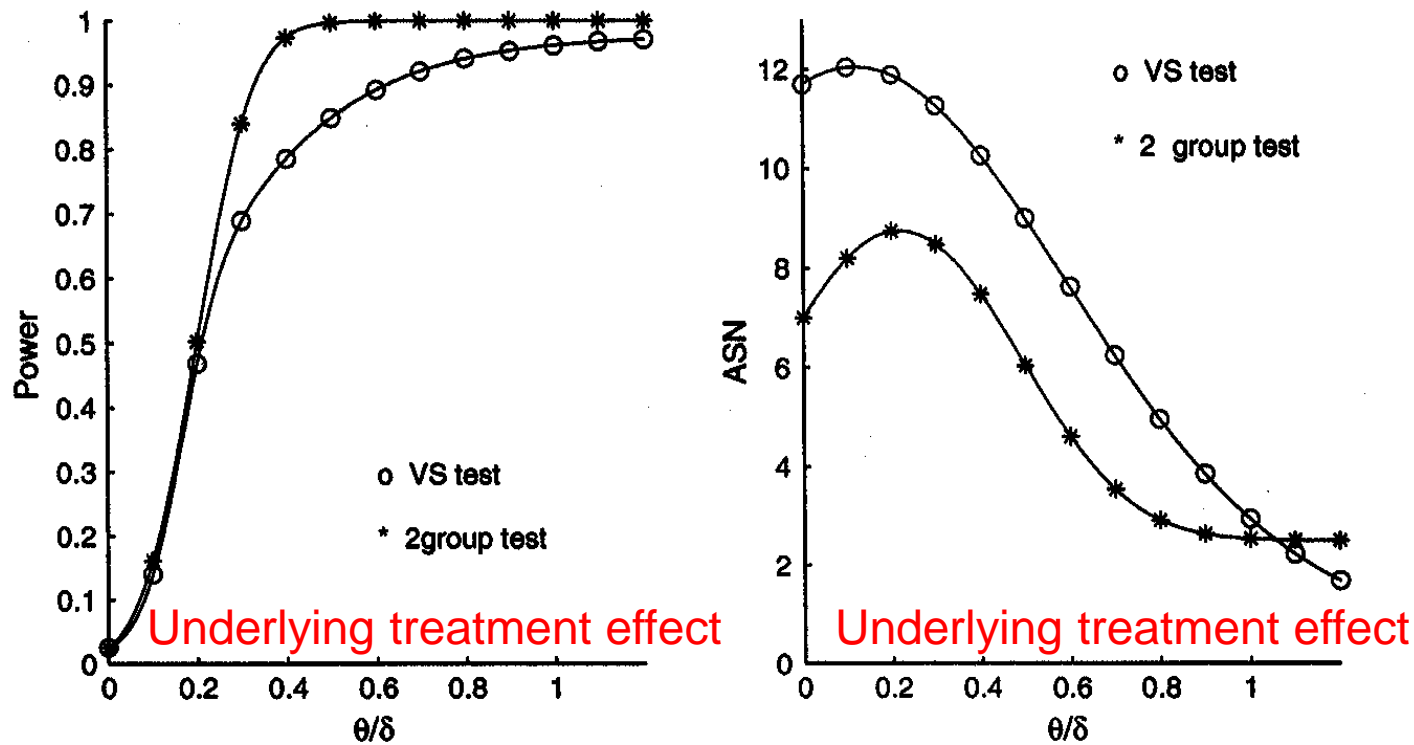


Figure 7. Power and ASN curves of the variance spending (VS) test and two-stage group sequential test. ASN scale is in multiples of the original fixed sample size,  $n$ .

# Question

- Can we compare ‘best’ adaptive and group sequential designs, with each using a fixed number of interim analyses?
  - Optimal group sequential design problem solved by Barber and Jennison, *Biometrika*, 2002
  - Similarly optimized of 2-stage adaptive designs are presented here with either:
    - Interim estimated treatment effect (Proschan & Hunsberger, *Bcs* 1995)
    - Minimal treatment effect of interest (Liu & Chi, *Bcs*, 2001)

# 2-stage Adaptive design

# 2-Stage Adaptive Design

## ■ Hypotheses

- $H_0: \theta=0$
- $H_a: \theta>0$

## ■ Interim analysis with test statistic $Z_1$

- Pre-specify  $a_1 < b_1$
- If  $Z_1 > b_1$  then stop and reject  $H_0$
- If  $Z_1 < a_1$  then stop and 'accept'  $H_0$
- If  $a_1 \leq Z_1 \leq b_1$ , continue to stage 2
  - Estimate required stage 2 sample size
  - Compute critical value for stage 2 data

# 2-Stage Adaptive Design

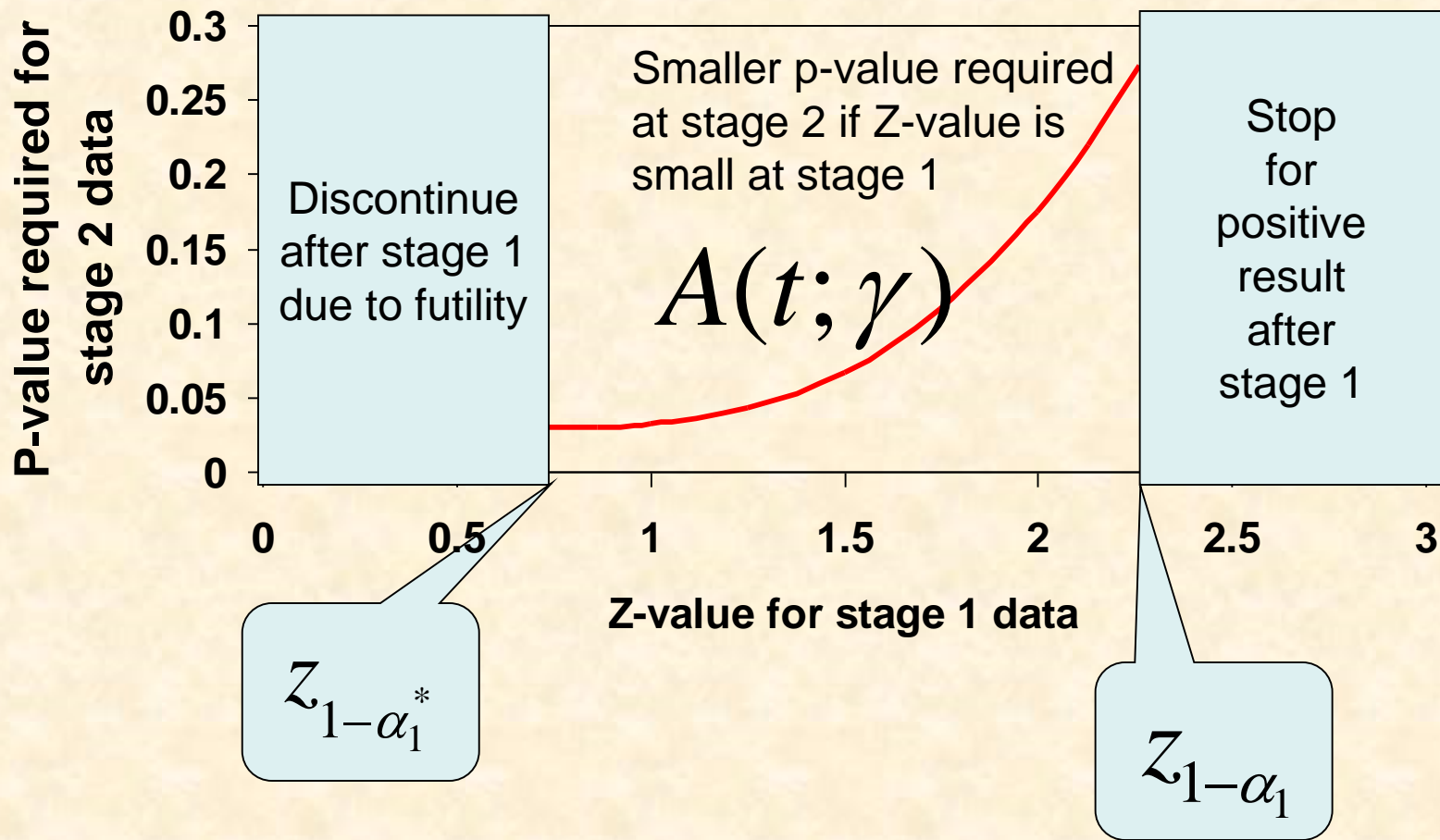
- Sample  $n_1$  subjects in stage 1
- Compute p-value for stage 1 data
  - May stop if positive or futile
- If trial continues, map observed stage 1 p-value to required stage 2 critical value
- Second stage sample size  $n_2$  determined at end of stage 1
- Compute observed p-value for stage 2 data (excluding stage 1 data) and compare to stage 2 critical value
  - Trial positive if 1<sup>st</sup> or 2<sup>nd</sup> stage is positive

# Conditional Power for Computing $n_2$

- Proschan and Hunsberger, Biometrics, 1995
  - Estimate  $\hat{\theta}$  from stage 1 data
  - Given this value and a critical value for stage 2, compute  $n_2$  to achieve desired power
- Liu and Chi, Biometrics, 2001
  - Substitute  $\theta_0$  a minimum value of interest, for  $\hat{\theta}$
  - This has the effect of reducing maximum sample size

# Conditional Error Function

## 2-stage adaptive design





# Properties of $A(t; \gamma)$

- Values in  $[0, 1/2)$ 
  - Require additional evidence in stage 2
- As a function of  $t$ ,  $A(t, \gamma)$  is
  - Defined on  $(-1, 1)$
  - Non-decreasing
- ‘Nuisance’ parameter  $\gamma$ 
  - $A(t, \gamma)$  increasing in  $\gamma$
  - Used to obtain the desired overall Type I error given the stage 1 critical values  $\alpha_1$  and  $\alpha_1^*$

# Type I Error

$$\alpha = \alpha_1 + \alpha_2$$

where

$$\alpha_2 = \int_{z_{1-\alpha_1}^*}^{z_{1-\alpha_1}} A(t; \gamma) \varphi(t) dt$$

$\gamma$  is typically used to adjust  $\alpha_2$  appropriately

# Generalizing $A(t; \gamma)$

- Want to choose from a broad class of  $A()$  functions to get a 'good' one
- Add 2 more parameters ( $\eta, \nu$ ) to allow flexibility in the shape and range of values
- Optimize over  $\alpha_1, \alpha_1^*, \eta$  and  $\nu$
- Still use  $\gamma$  to get desired overall Type I error given values of  $\alpha_1, \alpha_1^*, \eta$  and  $\nu$

# Power Function Family

$$A(t; \gamma, \eta, \nu) = \eta + \nu \left( \frac{t - z_{1-\alpha_1}^*}{z_{1-\alpha_1} - z_{1-\alpha_1}^*} \right)^\gamma$$

- $A()$  increasing in  $t$
- $A(z_{1-\alpha_1}^*; \gamma, \eta, \nu) = \eta$
- $A(z_{1-\alpha_1}; \gamma, \eta, \nu) = \eta + \nu$
- $\gamma$  determines shape

What to optimize?

# Optimization Problem Set-up

- Assume a prior distribution for  $\theta$
- Choose a 'loss' function (e.g., expected sample size)
- Fixed parameters:
  - $\alpha$  : Type I error
  - $1 - \beta$ : Power at minimum parameter value of interest  $\theta_0$
- Variable
  - $n_1$ , sample size at stage 1
  - $\alpha_1$ , stage 1 Type I error
  - $\alpha_1^*$ , probability of futility at stage 1 for  $\theta=0$
  - $\eta, \nu$  : determine shape of  $A()$

# Minimize wrt $n_1, \alpha_1, \alpha_1^*, \eta, \nu$

$$\int_{z_{1-\alpha_1^*}}^{z_{1-\alpha_1}} \int L(n_1, n_2(t; n_1, \alpha_1, \alpha_1^*, \eta, \nu)) dF(t; \theta, n_1) d\pi(\theta)$$

- $L()$  is the loss function
- $n_2(t;)$  is the sample size for stage 2 given a z-value of  $t$  was observed at stage 1 (formula not shown, but it is simple and is made of 'standard' components)
- $t$  is the z-value at stage 1
- $F()$  is a normal distribution with variance 1
- $\pi()$  is the prior distribution for  $\theta$

# Optimization

(in a nutshell)

- All functions are continuous in the given parameters
- Transform problem to an unconstrained optimization
- Use numerical integration to compute function
- Use off-the-shelf optimization for function without known derivatives (Powell's method)

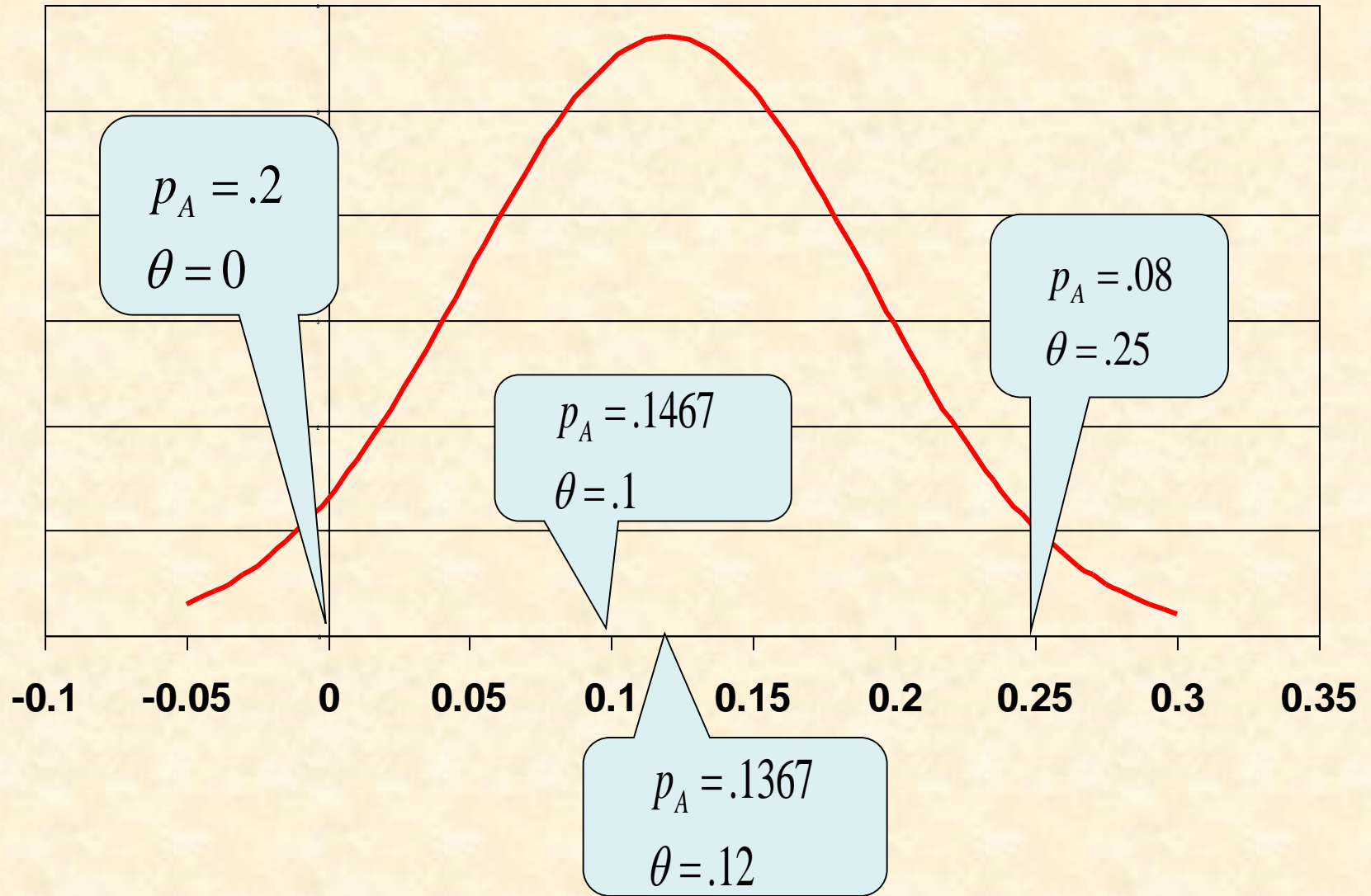


# Example

## ■ Binary outcome

- Control event rate estimate:  $p_C=20\%$
- Reduction by  $> 25\%$  (say,  $p_A=14.67\%$ ) considered clinically meaningful
  - $\theta=\arcsin(.20^{1/2})-\arcsin(.1467)^{1/2}=0.10$
- Reduction by 30% considered likely
  - $\theta=\arcsin(.20^{1/2})-\arcsin(.1367)^{1/2}=0.12$
- Moderately weak prior distribution:
  - $\theta \sim \text{Normal}(\mu=0.12, \sigma=.07)$
  - Implies ~5% chance of no effect or worse

# Prior density for $\theta$ (assume $p_C=0.2$ )



## Example (cont.)

- Suppose  $n_1$  observations ( $n_1/2$  per arm) collected in stage 1
- At that time

$$\hat{\theta} = \sqrt{n_1} \left\{ \arcsin(\sqrt{\hat{p}_C}) - \arcsin(\sqrt{\hat{p}_A}) \right\}$$

is distributed approximately  $\text{Normal}(\theta n_1^{1/2}, 1)$

# Designs compared

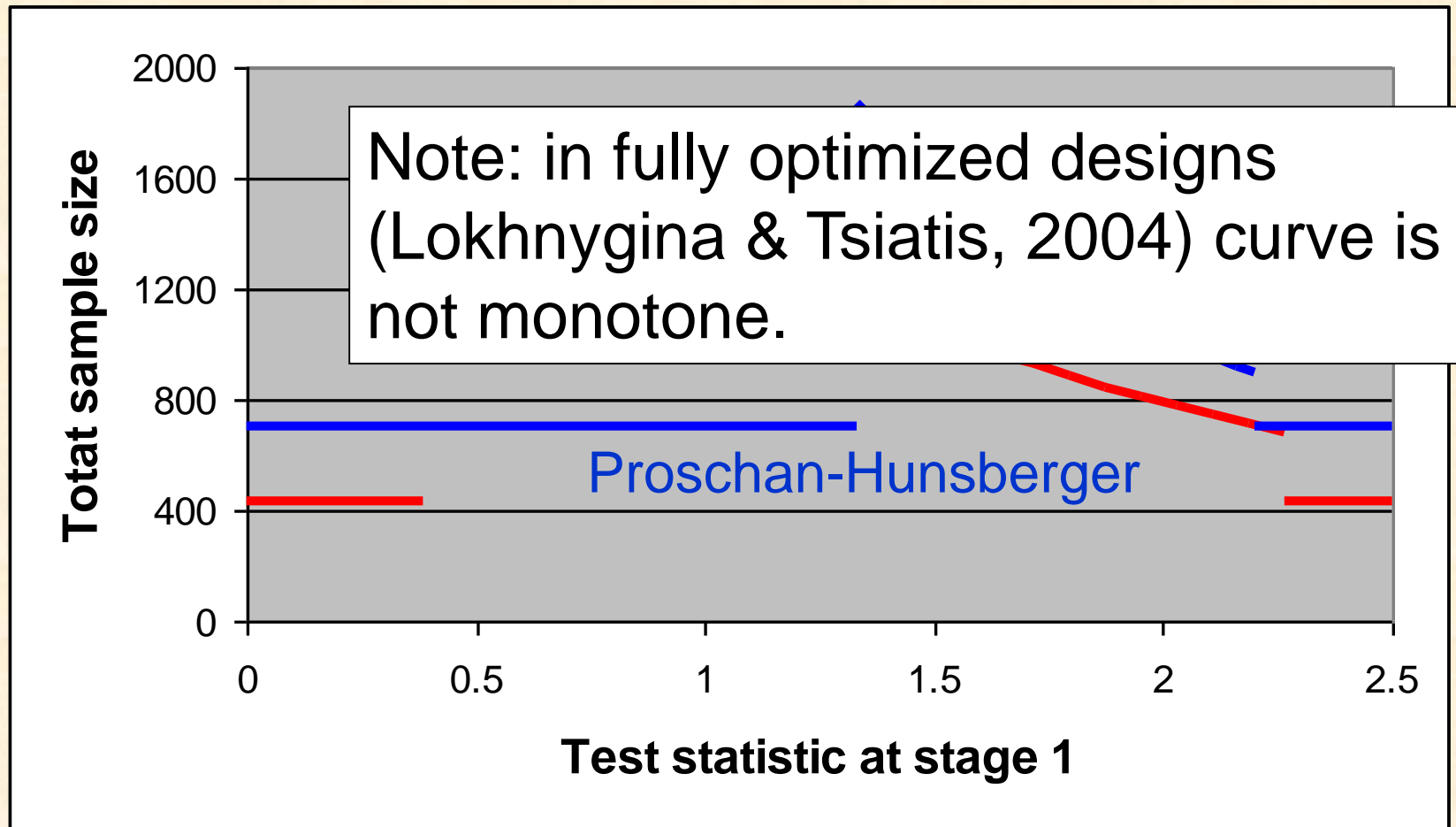
## ■ All have

- 90% power when  $\theta=0.1$
- Type I error (one-sided) = 0.025

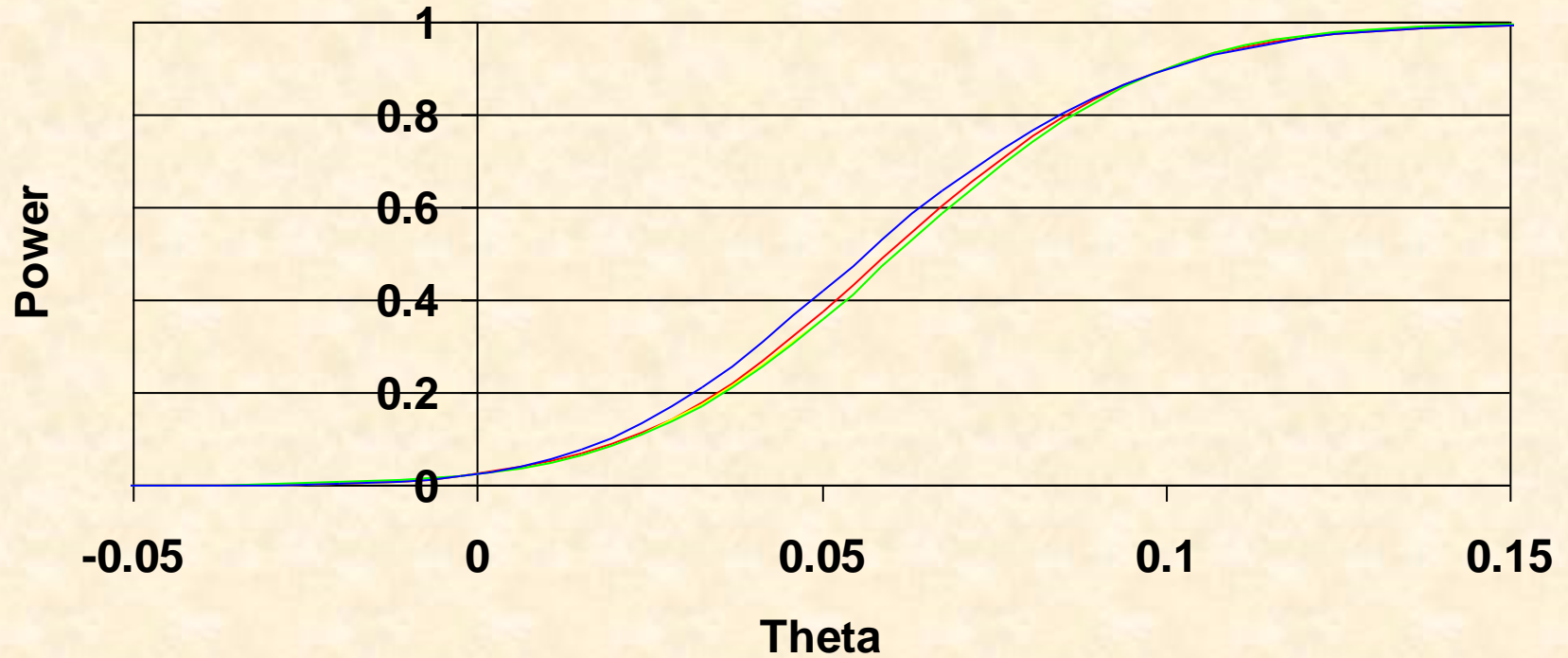
## ■ Designs

- Optimal adaptive (among Liu & Chi designs)
- Optimal group sequential
  - 2-stage
  - 3-stage
- Optimal adaptive (among Proschan-Hunsberger designs)

# Final Sample Size Based on Interim Analysis: Optimal Designs

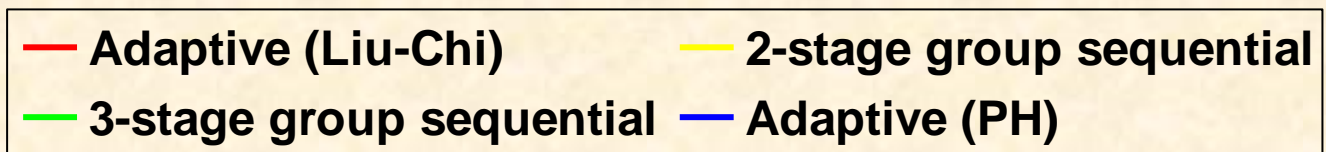
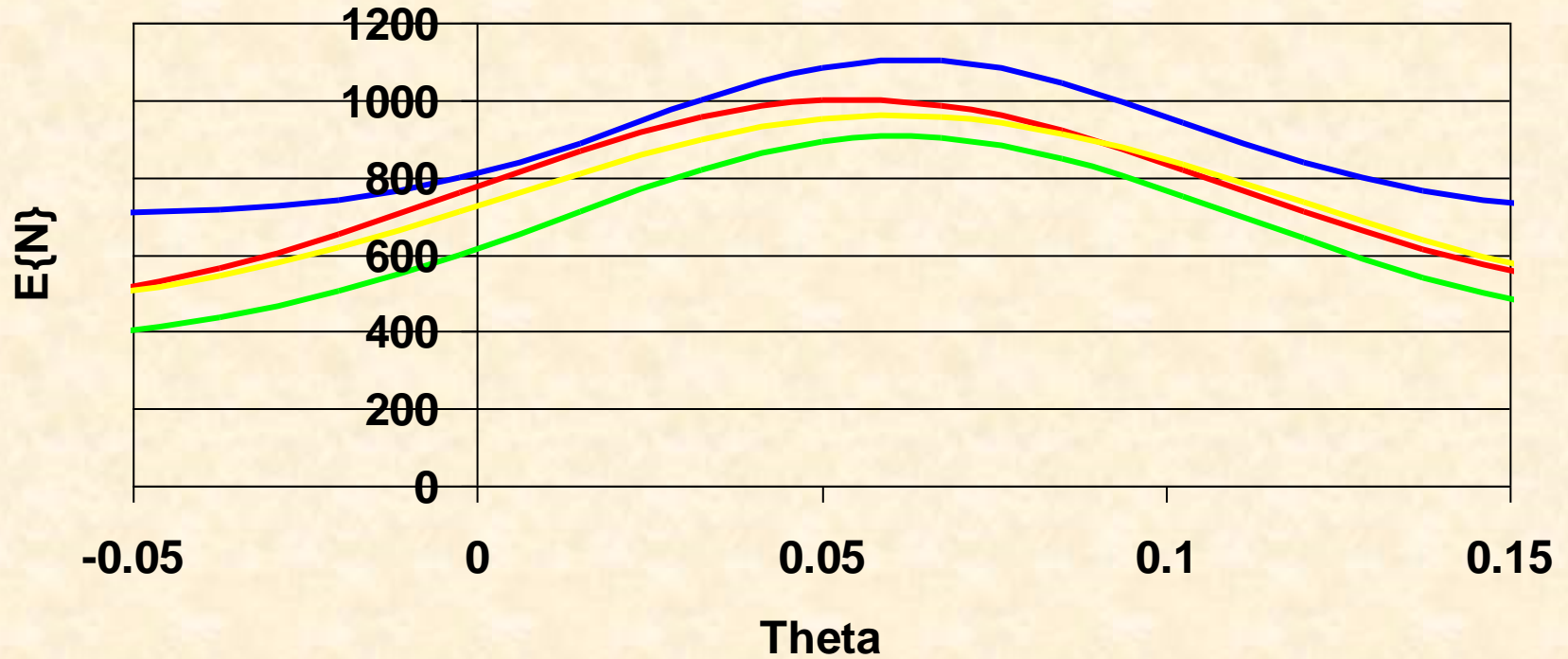


# Power of Optimal Tests

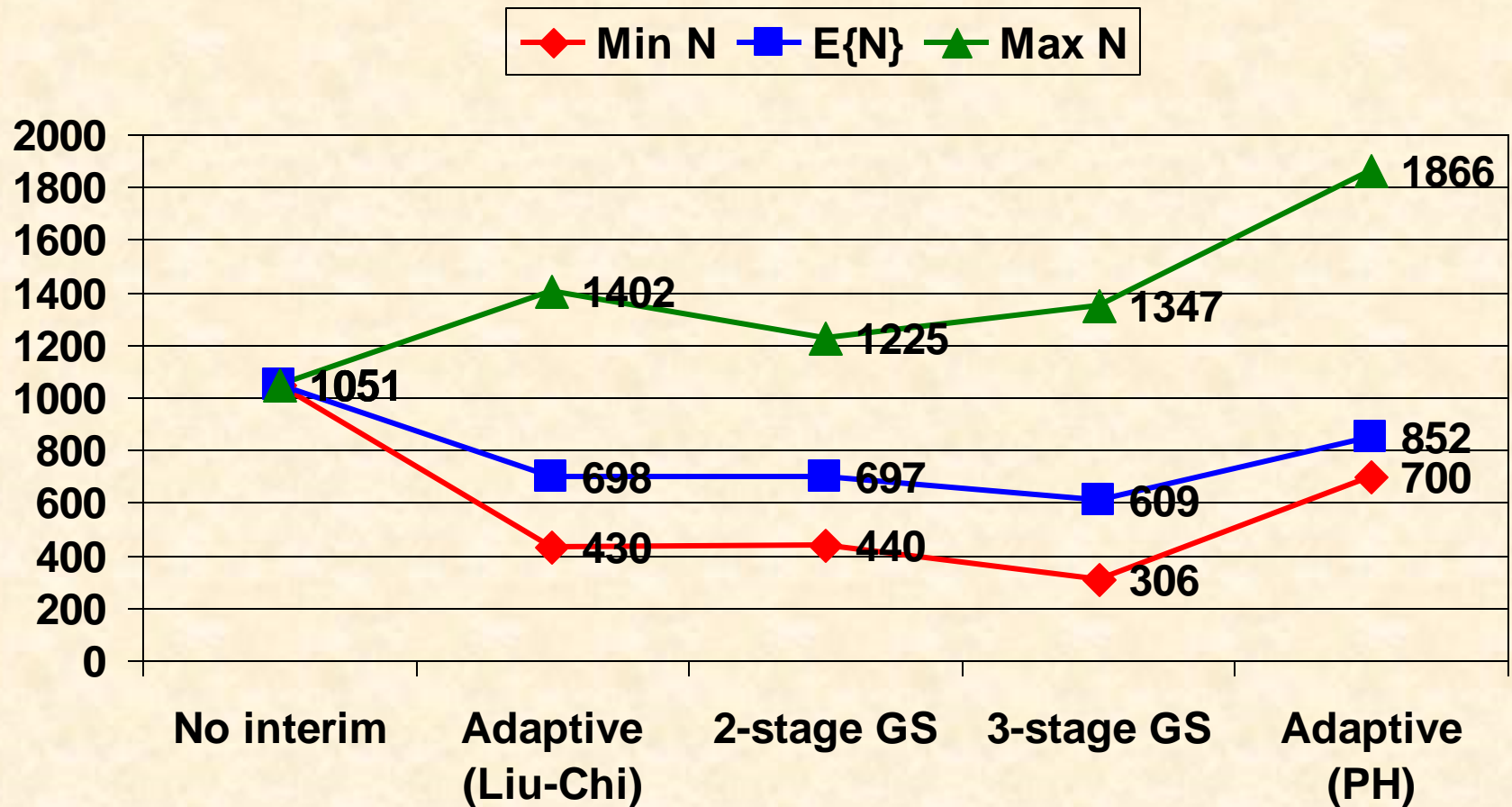


- Adaptive (Liu-Chi)
- 2-Stage Group Sequential
- 3-Stage Group Sequential
- Adaptive (Proschan-Hunsberger)

# $E\{N\}$ for Optimal Designs



# Sample Size for Optimal Designs





# Summary

- Adapting using a fixed, minimum treatment effect of interest (Liu-Chi method) appears to be better than adapting to the estimated effect at the time of interim analysis (Proschan-Hunsberger method)

# Summary

Assuming a single interim analysis we have shown an example where best adaptive and group sequential designs have essentially identical:

- Power over a range of parameter values
- Expected sample size when averaged over possible parameter values using a prior distribution

# Issues...

- Can we improve optimized adaptive designs by not insisting on constant conditional power?
  - Set maximum sample size (Posch, et al, 2001)
  - Lokhnygina & Tsiatis (2004)
- Other methods of comparing adaptive and group sequential designs
  - Qing Liu: ‘effectiveness’

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# Backup slides

- Conditional error function families

# Generalized Proportional Error Function Family

$$A(t; \gamma, \eta, \nu) = \eta \left\{ 1 - \Phi \left( \left[ \gamma (z_{1-\alpha_1} - t) \right]^\nu \right) \right\}$$

- $A()$  increasing in  $t$
- $A(z_{1-\alpha_1}; \gamma, \eta, \nu) = \eta$
- $\gamma$  and  $\nu$  together determine shape